

**Srinix College of Engineering, Balasore**  
Department of Computer Science & Engg.

**Basic Concept of Region Filling Algorithm in Computer  
Graphics**

**Prepared by**

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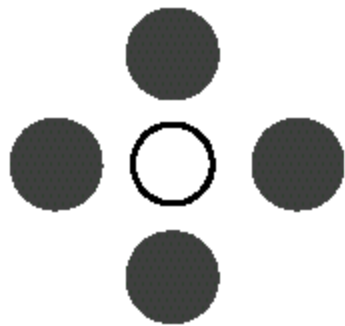
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# Region Filling

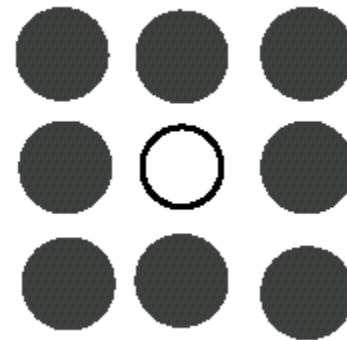
- **Seed Fill Approaches**
  - 2 algorithms: Boundary Fill and Flood Fill
  - works at the pixel level
  - suitable for interactive painting applications
- **Scan line Fill Approaches**
  - works at the polygon level
  - better performance

# Seed Fill Algorithms: Connectedness

- 4-connected region: From a given pixel, the region that you can get to by a series of 4 way moves (N, S, E and W)
- 8-connected region: From a given pixel, the region that you can get to by a series of 8 way moves (N, S, E, W, NE, NW, SE, and SW)



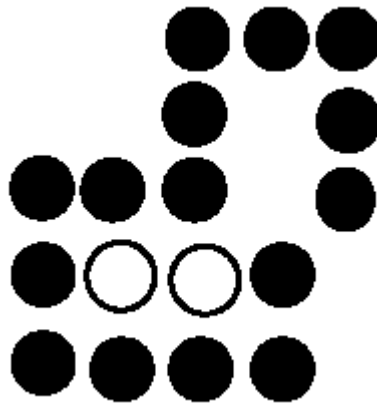
**4-connected**



**8-connected**

# Boundary Fill Algorithm

- Start at a point inside a region
- Paint the interior outward to the edge
- The edge must be specified in a single color
- Fill the 4-connected or 8-connected region
- 4-connected fill is faster, but can have problems:



# Boundary Fill Algorithm (cont.)

```
void BoundaryFill4(int x, int y,  
                  color newcolor, color edgecolor)  
{  
    int current;  
    current = ReadPixel(x, y);  
    if(current != edgecolor && current != newcolor)  
    {  
        BoundaryFill4(x+1, y, newcolor, edgecolor);  
        BoundaryFill4(x-1, y, newcolor, edgecolor);  
        BoundaryFill4(x, y+1, newcolor, edgecolor);  
        BoundaryFill4(x, y-1, newcolor, edgecolor);  
    }  
}
```

# Flood Fill Algorithm

- Used when an area defined with multiple color boundaries
- Start at a point inside a region
- Replace a specified interior color (old color) with fill color
- Fill the 4-connected or 8-connected region until all interior points being replaced

# Flood Fill Algorithm (cont.)

```
void FloodFill4(int x, int y, color newcolor, color oldColor)
{
    if(ReadPixel(x, y) == oldColor)
    {
        FloodFill4(x+1, y, newcolor, oldColor);
        FloodFill4(x-1, y, newcolor, oldColor);
        FloodFill4(x, y+1, newcolor, oldColor);
        FloodFill4(x, y-1, newcolor, oldColor);
    }
}
```

# Polygon Types

- simple convex, simple concave, non-simple (self-intersecting)
- want no holes, no intersections (line crossings)
- rectangles and triangles always simple convex



**simple  
convex**



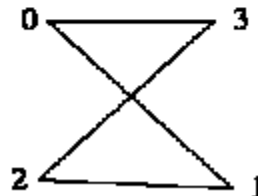
**simple  
concave**



**non-simple  
(self-intersection)**



**OK**



**Line Crossing**

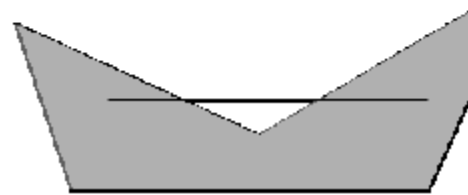
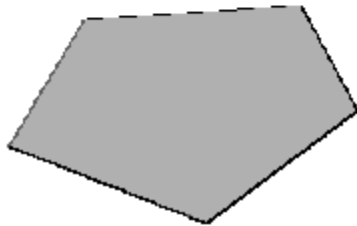


**Hole**

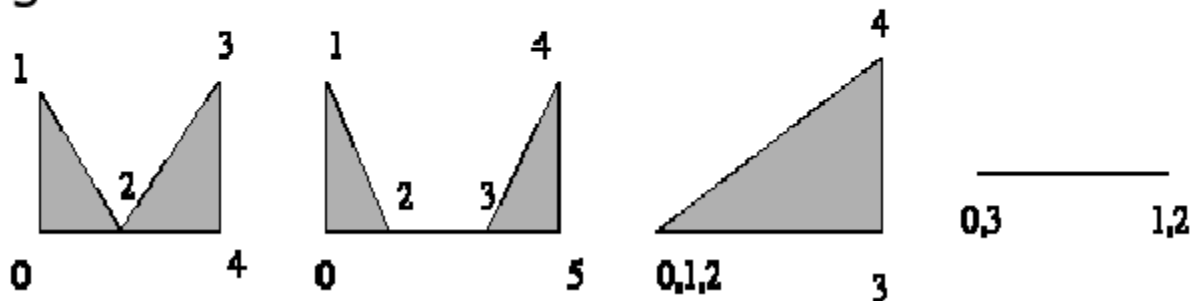


# Convex, Concave, Degenerate

- Convex polygons are preferable to concave
  - Polygon is convex if for any two points inside polygon, the line segment joining these two points is also inside.



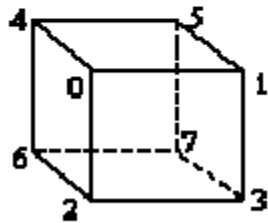
## ■ Degeneracies



# Polygon Representation

## ■ Polygon Representation

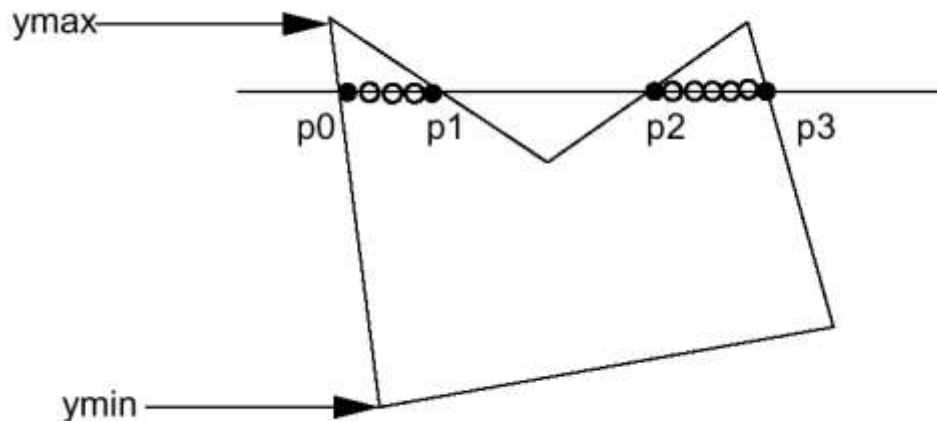
- ordered list of vertices
- avoids redundant storage and computations
- associate other information with vertices
  - | colors, normals, textures



faces		vertex list		
#	vertex list	#	x,y,z	
0	0,2,3,1	0	0,1,1	
1	1,3,7,5	1	1,1,1	
2	5,7,6,4	2	0,0,1	
3	4,6,2,0	3	1,0,1	
4	4,0,1,5	4	0,1,0	
5	2,6,7,3	5	1,1,0	
		6	0,0,0	
		7	1,0,0	

# Scanline Fill Algorithm

- Intersect scanline with polygon edges
- Fill between pairs of intersections
- Basic algorithm:  
For  $y = y_{\min}$  to  $y_{\max}$ 
  - 1) intersect scanline  $y$  with each edge
  - 2) sort intersections by increasing  $x$  [ $p_0, p_1, p_2, p_3$ ]
  - 3) fill pairwise ( $p_0 \rightarrow p_1, p_2 \rightarrow p_3, \dots$ )



# Spacial Handling

- Make sure we only fill the interior pixels

Define interior:

For a given pair of intersection points  
 $(X_i, Y)$ ,  $(X_j, Y)$

-> Fill ceiling( $X_i$ ) to floor( $X_j$ )

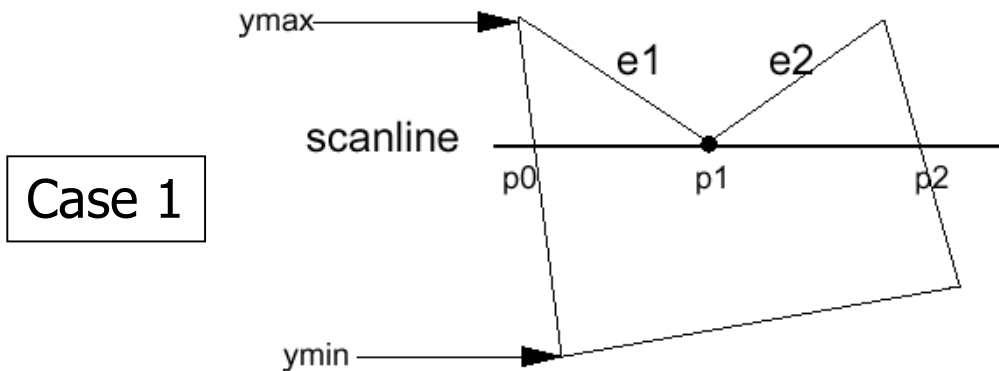
important when we have polygons adjacent  
to each other.

# Spacial Handling (cont.)

- Intersection has an integer  $X$  coordinate
  - > if  $X_i$  is integer, we define it to be interior
  - > if  $X_j$  is integer, we define it to be exterior  
(so don't fill)

# Spatial Handling (cont.)

- Intersection is an edge end point



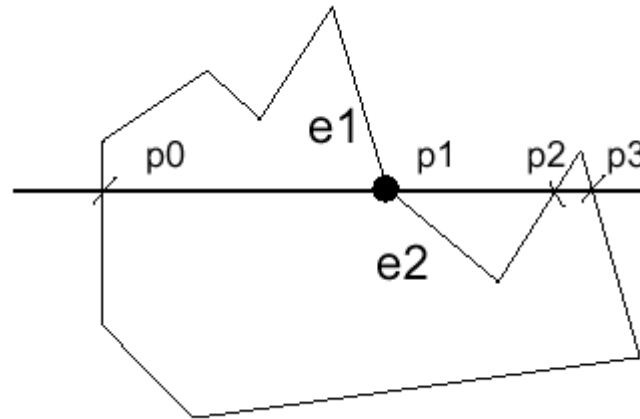
Intersection points:  $(p_0, p_1, p_2)$  ???

-> $(p_0, p_1, p_1, p_2)$  so we can still fill pairwise

->In fact, if we compute the intersection of the scanline with edge  $e_1$  and  $e_2$  separately, we will get the intersection point  $p_1$  twice. Keep both of the  $p_1$ .

# Spatial Handling (cont.)

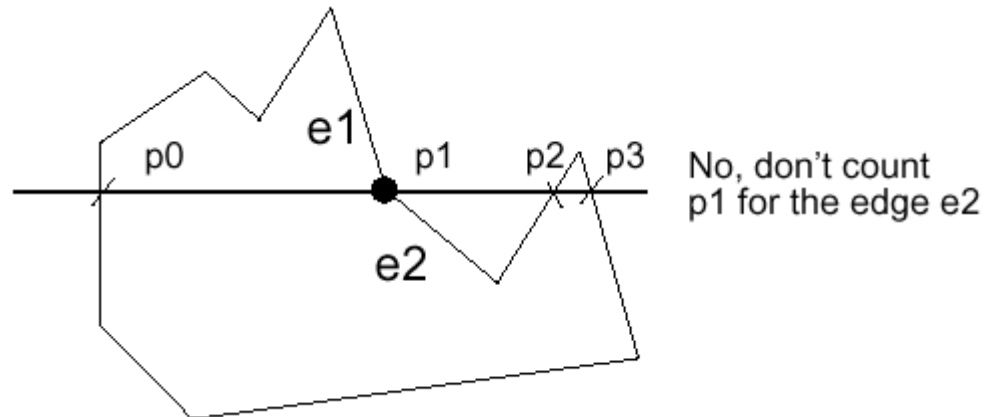
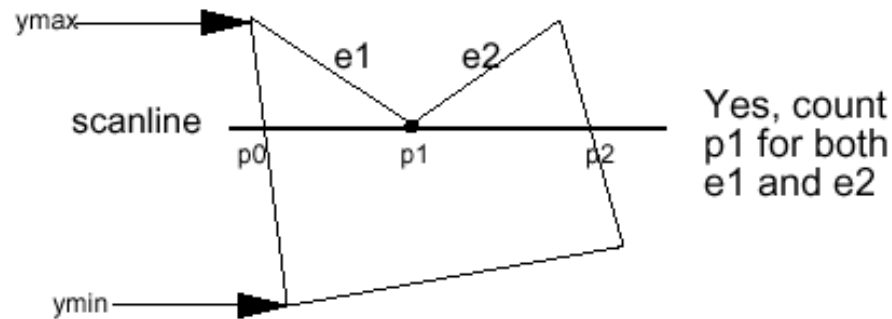
Case 2



However, in this case we don't want to count p1 twice (p0,p1,p1,p2,p3), otherwise we will fill pixels between p1 and p2, which is wrong.

# Spatial Handling (cont.)

Summary: If the intersection is the ymin of the edge's endpoint, count it. Otherwise, don't.





# References:

- Computer Graphics: Principles and Practice in C, by J. D. Foley, A. Van Dam, S. K. Feiner, J. F. Hughes. Addison-Wesley, 2nd ed.
- Essential Mathematics for Computer Graphics, fast, by John Vince. Springer.