

# **SRINIX COLLEGE OF ENGINEERING, BALASORE**



**DEPARTMENT OF  
COMPUTER SCIENCE & ENGINEERING**

**ASSIGNMENT ON  
COMPUTER GRAPHICS**

## **ASSIGNMENT-I**

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|-----|--|-----|
| 1.  | Explain Various Applications of Computer Graphics        | 12M |
| 2.  | Explain the Raster Scan Systems                          | 12M |
| 3.  | Explain the following concepts                           |     |
|     | (a) Random Scan  | 04M |
|     | (b) Boundary Fill  | 04M |
|     | (c) Flood Fill   | 04M |
| 4.  | Explain Pixel Addressing.                                | 06M |
| 5.  | Explain Ellipse Generating Algorithm.                    | 12M |
| 6.  | (a) What are DDA and Explain DDA Line Drawing Algorithm? | 06M |
|     | (b) Explain Bresenham's Line Drawing Algorithm.          | 06M |
| 7.  | (a) What Flat-Panel Displays?                            | 06M |
|     | (b) Explain Graphics Monitors and Workstations.          | 06M |
| 8.  | Explain  |     |
|     | (a) DVST   | 04M |
|     | (b) Data Glove   | 04M |
|     | (c) Image Scanners                                       | 04M |
|     | (d) Graphics Functions                                   | 04M |
| 9.  | (a) Explain Midpoint Circle Generating Algorithm.        | 06M |
|     | (b) Explain Midpoint Ellipse Generating Algorithm.       | 06M |
| 10. | (a) Describe Output primitives briefly.                  | 06M |
|     | (b) Explain Scan-Line Polygon Fill Algorithm             | 06M |

## **ASSIGNMENT-II**

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| 1. (a) What is Geometric Transformation?                                     | 02M |
| (b) Explain Matrix Representations and Homogeneous Coordinates.              | 10M |
| 2. (a) Explain Reflection and Shear?   | 06M |
| (b) Describe General Pivot-Point Rotation?                                   | 06M |
| 3. Explain Basic Transformations   | 12M |
| 4. (a) What is Composite Transformations?                                    | 06M |
| (b) Describe General Fixed-Point Scaling?                                    | 06M |
| 5. (a) What is Affine Transformation? Explain.                               | 06M |
| (b) Describe General Composite Transformations and Computational Efficiency. | 06M |
| 6. (a) Explain the Transformations between Coordinate Systems                | 06M |
| (b) Write 3D Coordinate-Axes Rotations.                                      | 06M |
| 7. (a) Describe 3D Transformation Functions.                                 | 06M |
| (b) Explain Modeling and Coordinate Transformation .                         | 06M |
| 8. (a) Explain 3D Translation and Scaling                                    | 06M |
| (b) Describe Rotations with Quaternions.                                     | 06M |
| 9. Explain Raster Methods for Transformations                                | 12M |
| 10. Write Concatenation Properties and General Scaling Directions?           | 12M |

### **ASSIGNMENT-III**

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| 1. Explain Viewing Pipeline.  | 06M |
| 2. Explain Viewing Coordinate Reference Frame                       | 06M |
| 3. (a) What is Window-to-Viewport Coordinate Transformation         | 05M |
| (b) Explain Clipping Operations.                                    | 07M |
| 4. Explain Cohen-Sutherland Line Clipping detail.                   | 12M |
| 5. (a) Explain Liang-Barsky Line Clipping.                          | 06M |
| (b) Explain Sutherland-Hodgeman Polygon Clipping.                   | 06M |
| 6. (a) Describe Two-Dimensional Viewing Functions.                  | 04M |
| (b) Explain Projections.  | 08M |
| 7. Explain Three Dimensional Viewing Functions.                     | 06M |
| 8. (a) Describe General Parallel-Projection Transformations?        | 06M |
| (b) Describe Spline Representation.                                 | 06M |
| 9. Describe B-Spline Curves and Surfaces and its Properties.        | 12M |
| 10. (a) Explain Hermite Interpolation and Kochanek-Bartels Splines. | 06M |
| (b) Explain Bezier Curves and Surfaces.                             | 06M |
| 11. Explain Cubic Spline Interpolation                              |     |
| 12. Explain   | 12M |
| (a) Ellipsoid   |     |
| (b) Blobby Objects  |     |
| (c) Nonuniform B-Splines  |     |
| 13. Explain   | 12M |
| (a) Sweep Representation  |     |
| (b) Octree  |     |
| (c) Constructive Solid-Geometry Methods                             |     |

## **ASSIGNMENT-IV**

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|-----|---|-----|
| 1.  | (a) What is Back-Face Detection?                                    | 06M |
|     | (b) Explain the benefits of Wireframe Method?                       | 06M |
| 2.  | (a) Explain Classification of Visible –Surface Detection Algorithms | 06M |
|     | (b) Describe Depth-Buffer Method                                    | 06M |
| 3.  | Explain A-Buffer Method.  | 06M |
| 4.  | Explain the following   |     |
|     | (a) Scan-Line Method  | 04M |
|     | (b) Curved Surfaces   | 04M |
|     | (c) Surface Contour Plots   | 04M |
| 5.  | Explain the Visibility-Detection Functions                          | 12M |
| 6.  | (a) What is BSP-Tree Method   | 06M |
|     | (b) Describe Area-Subdivision Method.                               | 06M |
| 7.  | (a) What is Ray-Casting and explain it?                             | 05M |
|     | (b) Explain Curved Surfaces.  | 07M |
| 8.  | Explain the importance of Depth-Buffer Method                       | 06M |
| 9   | (a) Explain the Difference between Depth-Buffer and A-Buffer.       | 06M |
|     | (b) Explain the importance of Surface Contour Plots.                | 06M |
| 10. | Explain the Depth-Sorting Method in detail.                         | 06M |

## **ASSIGNMENT-V**

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|----|---|-----|
| 1. | (a) What is Morphing? Explain briefly.            | 06M |
|    | (b) Explain the Simulating Acceleration.          | 06M |
| 2. | (a) Explain the Motion Specification.             | 06M |
|    | (b) Describe Goal-Directed Systems.               | 06M |
| 3. | Explain the importance of Motion Specification    | 12M |
| 4. | (a) Explain the Design of Animation Sequences.    | 06M |
|    | (b) Explain general Computer-Animation Functions. | 06M |
| 5. | Describe Raster Animations.                       | 06M |
| 6. | Explain Key-Frame Systems.                        | 06M |
| 7. | (a) Describe Kinematics and Dynamics.             | 06M |
|    | (b) Explain the Direct Motion Specification.      | 06M |